



## STUDENT SUSTAINABILITY COMMITTEE

### Funding Application – Step 1

Please submit this completed application and any relevant supporting documentation by the deadline listed on the SSC website to [Sustainability-Committee@Illinois.edu](mailto:Sustainability-Committee@Illinois.edu). The Working Group Chairs will be in contact with you regarding any questions about the application. If you have any questions about the application process, please contact the SSC at [Sustainability-Committee@Illinois.edu](mailto:Sustainability-Committee@Illinois.edu).

### General Information

**Project Name:** Automated Construction Systems with Up-cycled Materials

**Total Amount Requested from SSC:** \$35,000

**Project Topic Area(s):**  Energy       Education       Food & Waste  
 Land       Water       Transportation

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### Contact Information

Applicant Name: Kevin Erickson, Architect, Associate Professor + Program Chair  
Unit/Department: School of Architecture  
Email Address: [kne@illinois.edu](mailto:kne@illinois.edu)  
Phone Number: 810.434.8690

#### Project Team

Name	Department	Email
Kevin Erickson	Architecture – Faculty	<a href="mailto:kne@illinois.edu">kne@illinois.edu</a>
Martin Ruaber	Architecture – Student	<a href="mailto:rauber2@illinois.edu">rauber2@illinois.edu</a>
Justine Yu	US Army Corps of Engineers	<a href="mailto:Justine.A.Yu@usace.army.mil">Justine.A.Yu@usace.army.mil</a>

## **Project Information**

Please provide a brief background of the project, the goals, and the desired outcomes:

Labor and materials are the two largest costs for the construction and maintenance of buildings in the developed world. This application seeks support to test automated construction systems with up-cycled materials, investigating how advances in technology and manufacturing can help reduce inefficiency and waste in the construction process.

In March 2017, the School of Architecture acquired a high-payload, 6-axis robotic arm. After initial testing, Prof. Kevin Erickson began a collaborative research project with U.S. Army Engineer Research and Development Center's Construction Engineering Research Laboratory (ERDC-CERL). During the Fall 2017 semester, Prof. Erickson's graduate seminar course, along with ERDC-CERL, explored the possibilities of automated construction – 3D-printing using the School's robotic arm. On September 21, students from Prof. Erickson's graduate seminar course along with a team from ERDC-CERL, successfully printed one of the world's first concrete structures, with reinforcing and aggregate, using a robotic arm known to exist.

This application seeks to take that process a step further by using locally sourced bio-based and other up-cycled materials, refining those materials with a non-toxic, organic binding agent and 3D-printing full-scale building components using the School's robotic arm.

Please provide a brief summary of how students will be involved in the project:

Similar to our research with CERL, students will play an integral part in this request. This research seeks to draw students from across campus into a undergrad/ graduate seminar course during the Fall 2018 semester. In the summer leading up to this course students will be employed to conduct research and tests. Following the seminar course, a select group of students will be asked to continue working on the project.

Please provide a brief summary of the project timeline:

Summer 2018 – Research and test up-cycled materials that can be 3D-printed (saw dust from our woodshop, cornstalks, etc.). Faculty, students, and our partners at ERDC-CERL will conduct the research and testing.

Fall 2018 – Offer an Interdisciplinary Graduate Seminar Course (up to 15 students) to design a small building or building component that can be fabricated using automated robotic processes. Building on the materials research, apply an up-cycled material to the automated construction process and create a full-scale prototype. Lastly, students will be asked to document and test their prototypes for structural stability, calculate embodied energy, and explore potential applications.

Spring 2019 – Compile research and documentation from Summer and Fall 2018 sessions. Develop that knowledge into peer-reviewed journal articles while investigating further applications for implementation on campus and for other applicable situations. This would ideally be executed with a Graduate Research Assistant and student hourly employees.

Additional comments

\$12,000 – Graduate Research Assistant (2 semesters at 25% appointment)

\$ 4,000 – Student Hourly Employees

\$ 6,000 – Faculty Summer Stipend

\$ 5,000 – Robot Configuration (fixtures, mounts, hoses, pumps, etc.)

\$ 6,500 – Up-Cycled Materials (gathering, processing, binders, etc.)

\$ 1,500 – Structural Testing Prototypes

**\$35,000 – Preliminary Budget Total**

# ROBOTS + ARCHITECTURE

## ARCH 576 Graduate Seminar I Fall 2017

Collaboration with U.S. Army Engineer Research and Development Center's Construction Engineering Research Laboratory (ERDC-CERL) to 3D-print a 3'x3'x8" structural concrete wall using the School of Architecture's robotic arm.

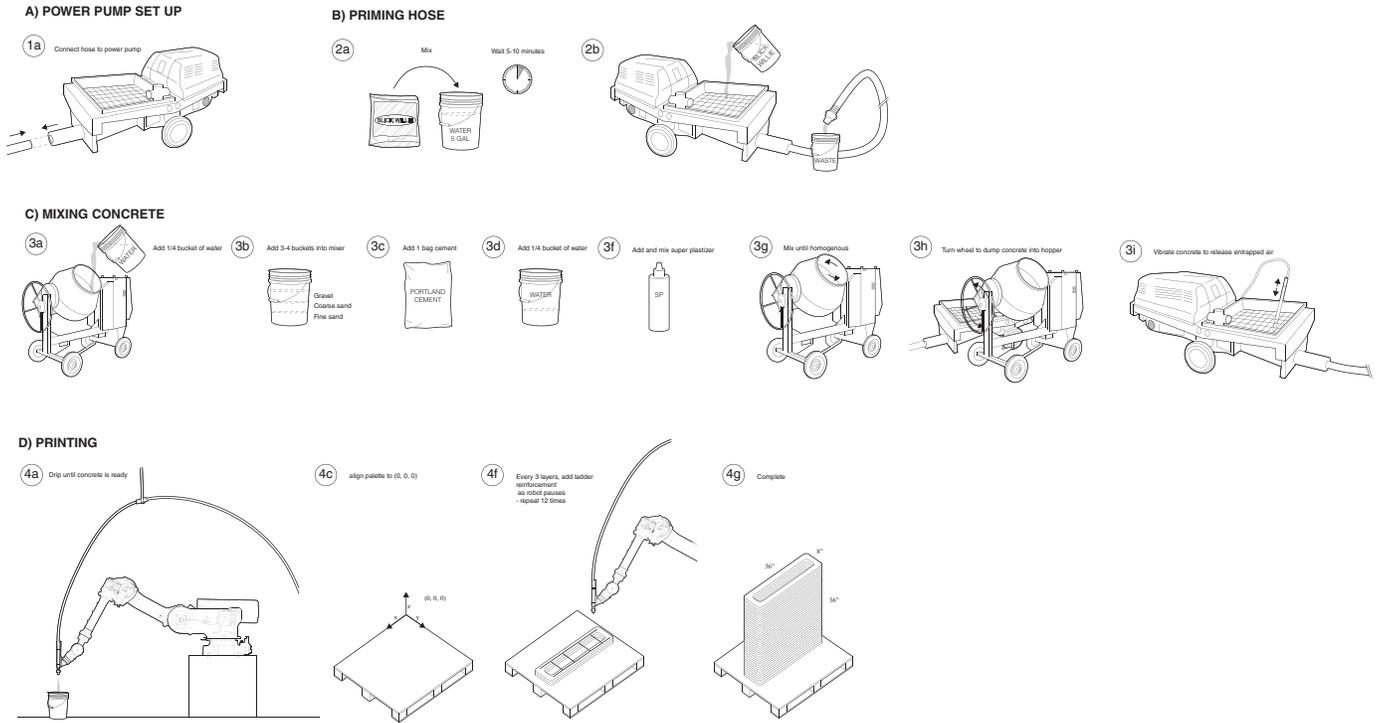


Fig 1. Diagram of 3D-printing Process



Fig 2. Fall 17' Graduate Seminar Students Preparing Materials for Printing



Fig 3. Robotic Arm Configured for Concrete Printing



Fig 4. Steel-reinforced 3'x3'x8" Concrete Printed Wall

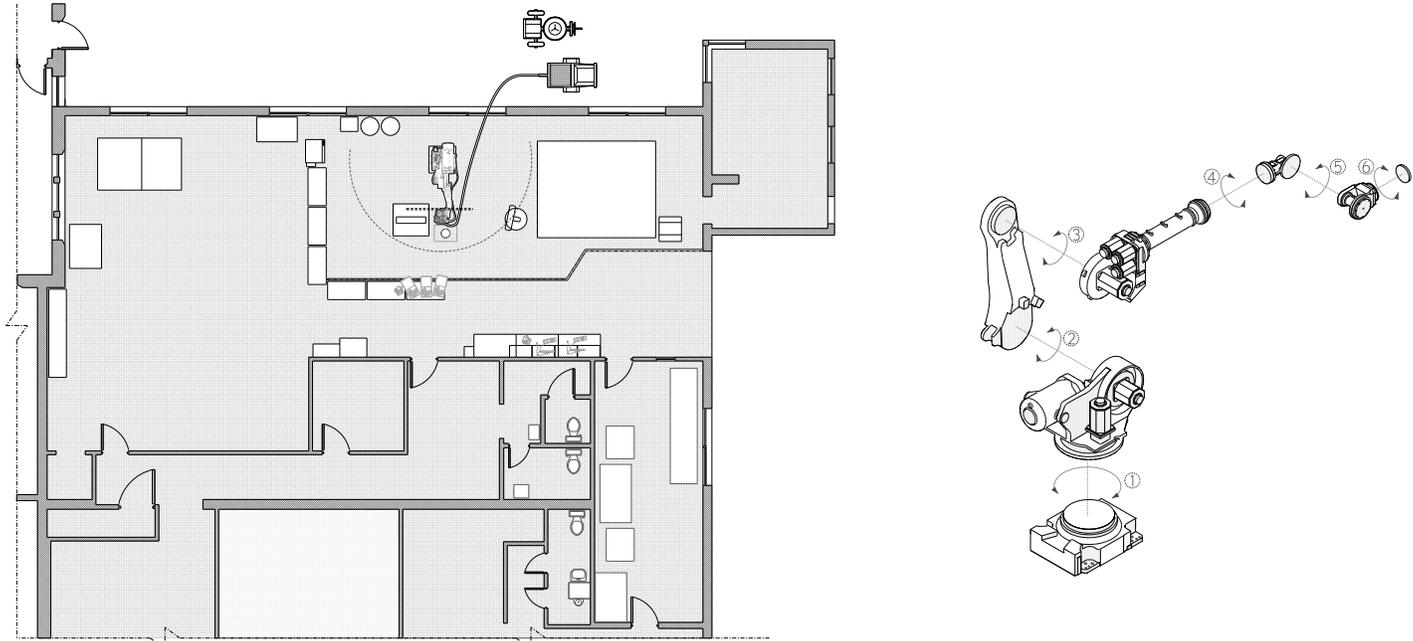


Fig 5. Diagram of Robot/ Printing Configuration